

# **AGI WESTFIELD**

## ***A 15-Year Journey into Robotic Welding***

***How to turn robots into money-making machines***

# A Bit About Me...



- Civil Engineering Graduate, 2012 – U of M
- MBA Graduate, 2018 – U of M
- Lean Manufacturing Coordinator, 2018
- Continuous Improvement Manager, 2019
- Operations Manager, 2019
- Love the outdoors, fishing, reading
- Powersports
- New dad



# Presentation Overview



- Company Background
- Brief History
- Why Robots?
- Getting Started with Robotic Welding
- Challenges to Overcome before Robots will be Successful
- Maximizing Output
- Return on Investment
- Robotic Material Handling



# Westfield Background



- Founded in 1950
- World's largest manufacturer of portable grain augers
- 162,000 ft<sup>2</sup> of production space
- 350+ production employees
- Day shift, night shift and weekend shift





# The Facility



- CNC Lasers
- CNC Saws
- CNC Lathes & Mills
- CNC Brakes
- Tube Mill
- Manual Welding
- Robotic Welding
- Powder Coat Paint Line
- Assembly
- Packaging
- Shipping



# What do we build?



## Swing Augers

- Used to get grain from a truck to a storage bin

## Truck Loading Augers

- Used to get grain from a storage bin to a truck

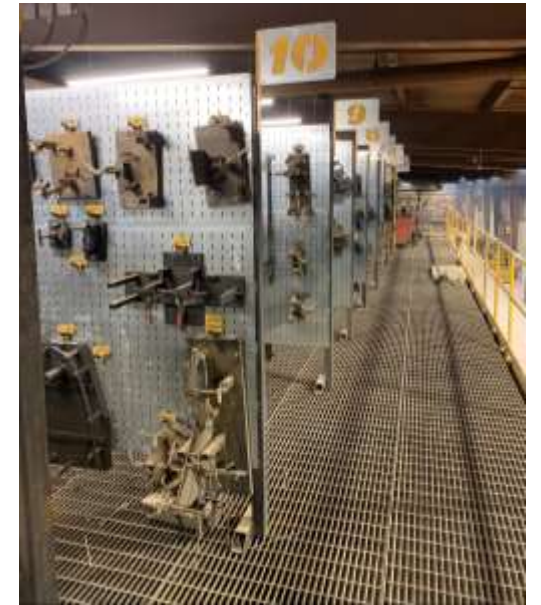




# Production Facts



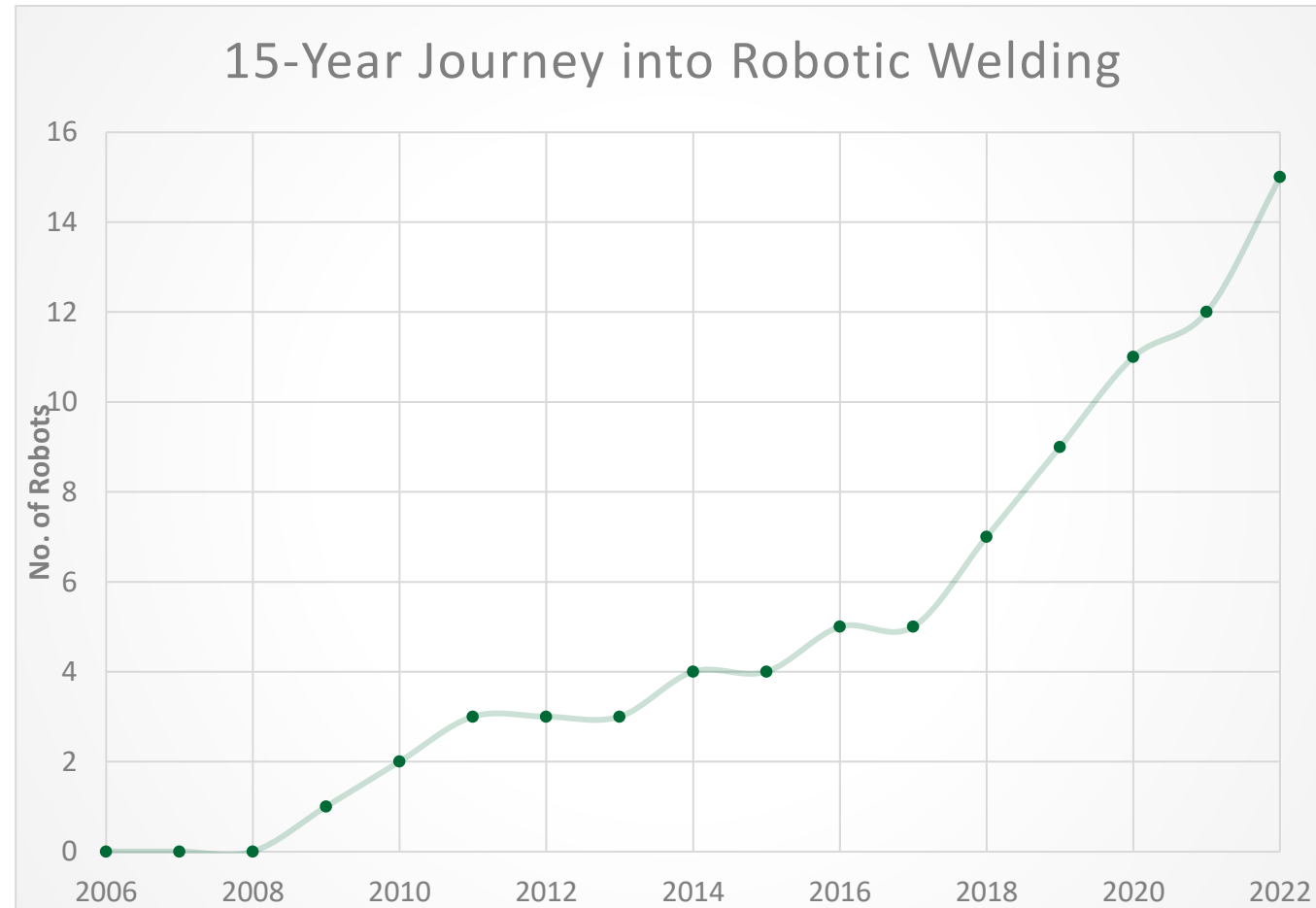
- A typical auger:
  - Assembled from over 600 different manufactured components
  - Built with over 4,200 inches of welding
  - ~40,000,000 inches of welding per year...



# Robotic Journey Milestones



- 2006 – Lean Journey Commences
- 2007 – Powder Coat Line Installed
- 2008 – Capacity for more welding
- 2009 – 1<sup>st</sup> Robotic Welder
- 2014 – Robotic Frame Welding
- 2018 – Fixtures Department is born
- 2021 – Robotic Tube Welding
- 2021 – First Non-Welding Robot
- 2022 – 14<sup>th</sup> & 15<sup>th</sup> robots





# Why Robots?

- People make mistakes
- People are unpredictable
- People are hard to find



?



Cold Lap



Burn Through



Porosity



Spatter

# Why Robots?

- Robots are consistent
- Robots are faster
- Robots produce a higher quality weld





# Why Robots?





# Why Robots?

- Robots are consistent
- Robots are faster
- Robots produce a higher quality weld
- Robots are easier to staff



# Getting Started with Robotic Welding

## Step 1: Pick the right part(s)

- Some considerations:

- Weld length **X**
- Accessibility **✓**
- Warping **✓**
- Volume **X**
- Simplicity **✓**
- Input parts **✓**



VS





# Getting Started with Robotic Welding

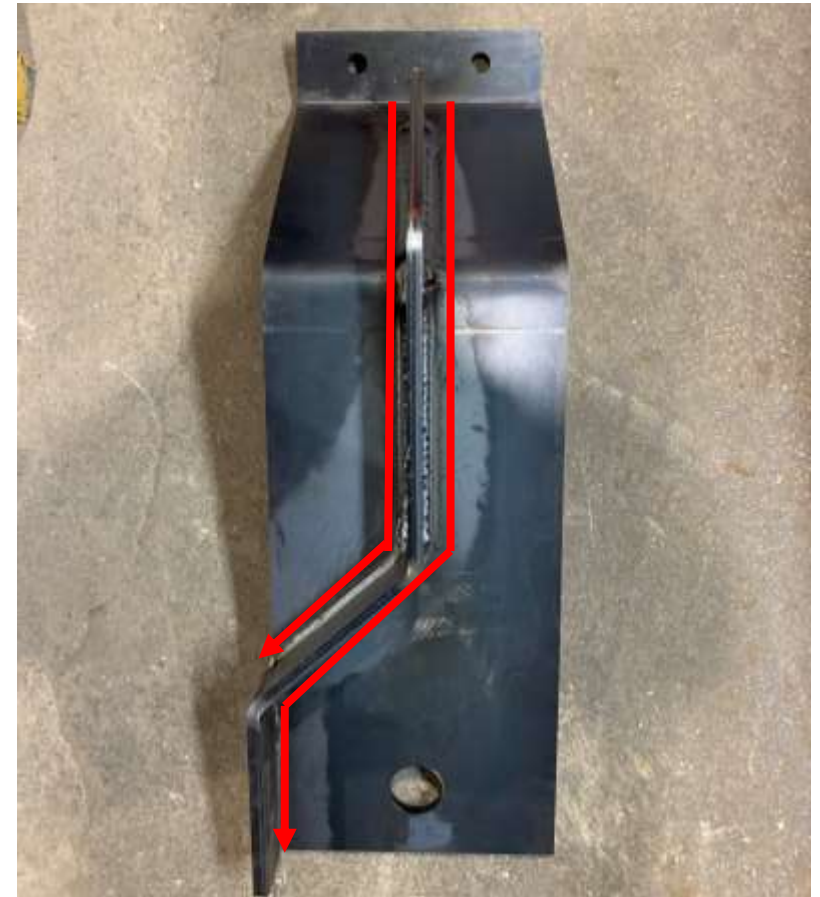
## Step 1: Pick the right part(s)

- Some considerations:

- Weld length ✓
- Accessibility ✓
- Warping ✓
- Volume ✓
- Simplicity ✓
- Input parts ✓



VS





# Getting Started with Robotic Welding



## Step 2: Build a fixture and perfect it with manual welding

- Some considerations:
  - Keep it simple
  - If the part warps manually welding, it will warp more on a robot
  - Make sure the designer, fabricator, and welder communicate
  - Watch the welder manually weld it
  - Outsourcing the fixture design/build is expensive and not as iterative



# Getting Started with Robotic Welding

## Step 3: Buy the right robot

- Some considerations:
  - Setup time is downtime unless the robot can keep welding
  - Footprint
  - Material flow
  - Robot reach
  - Payload
  - # of robots
  - Accessibility
  - Technical support







Panasonic



Performer Series

MANUFACTURING



# Getting Started with Robotic Welding

## Step 3: Buy the right robot

- Some considerations:
  - Setup time is downtime unless the robot can keep welding
  - Footprint
  - Material flow
  - Robot reach
  - Payload
  - # of robots
  - Accessibility
  - Technical support

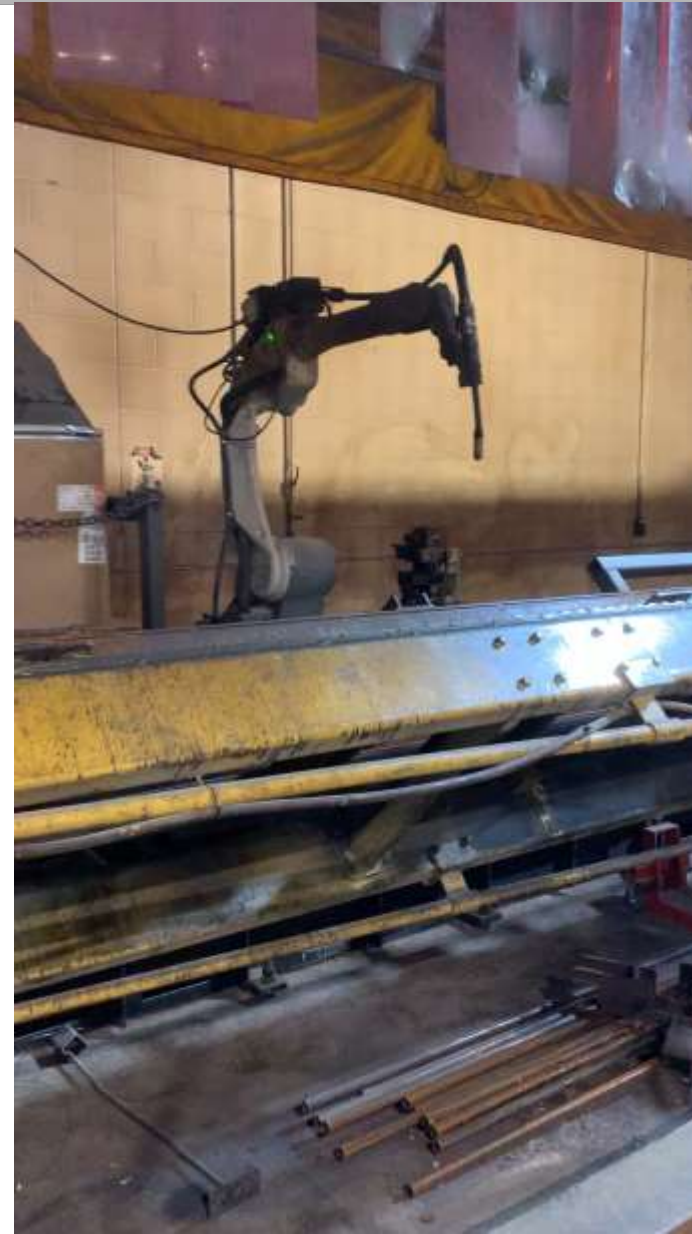


# Getting Started with Robotic Welding



## Step 3: Pick the right robot

- Some considerations:
  - Setup time is downtime unless the robot can keep welding ✓
  - Footprint ✓
  - Material flow ✗
  - Robot reach ✓
  - Payload ✓
  - # of robots ✓
  - Accessibility ✓
  - Technical support ✓





# Getting Started with Robotic Welding



- Don't rely on the robot... yet
- Some considerations:
  - Programming takes time
  - Expect some trial and error
  - Use the robot's output as supplementary





# Challenges to Overcome before Robots will be Successful



- When the first attempt fails
  - Stick with it
- Employee resistance and negativity
  - Need early wins
  - Involve your employees
- Variability
  - Robots hate it so eliminate it



# Challenges to Overcome before Robots will be Successful



- Developing inhouse experts
  - Good robots require great people
- Training operators
  - Need internal training
- Troubleshooting
  - Need problem solvers
- Spare parts
  - Wear parts vs “I screwed up” parts



# Maximizing Output



- Welding is the only value add process a robotic welder performs so maximize it
- Some considerations:
  - Touch sensing is a waste process, only use it when necessary
  - Perfect upstream processes if incoming parts are varying
  - Build robust fixtures
  - Design for manufacture





# Maximizing Output



- Welding is the only value add process a robotic welder performs so maximize it
- Some considerations:
  - Touch sensing is a waste process, only use it when necessary
  - Perfect upstream processes if incoming parts are varying
  - Build robust fixtures
  - Design for manufacture



# Maximizing Output



- Establish a robust process, train your operators and set a target
- Some considerations:
  - Repeatable work requires a repeatable process
  - Listen to the operators
  - Measure what matters
  - Arc on time vs OEE
  - Celebrate success

STEP 1: Unload  
Welded Part



STEP 2: Put Parts  
Into Jig



STEP 3: Clamp the Parts



STEP 4: Press start



# Maximizing Output

- Continuously monitor, improve, and train
- Some considerations:
  - Hide the hammers
  - Watch for the grinders
  - Operators like to weld

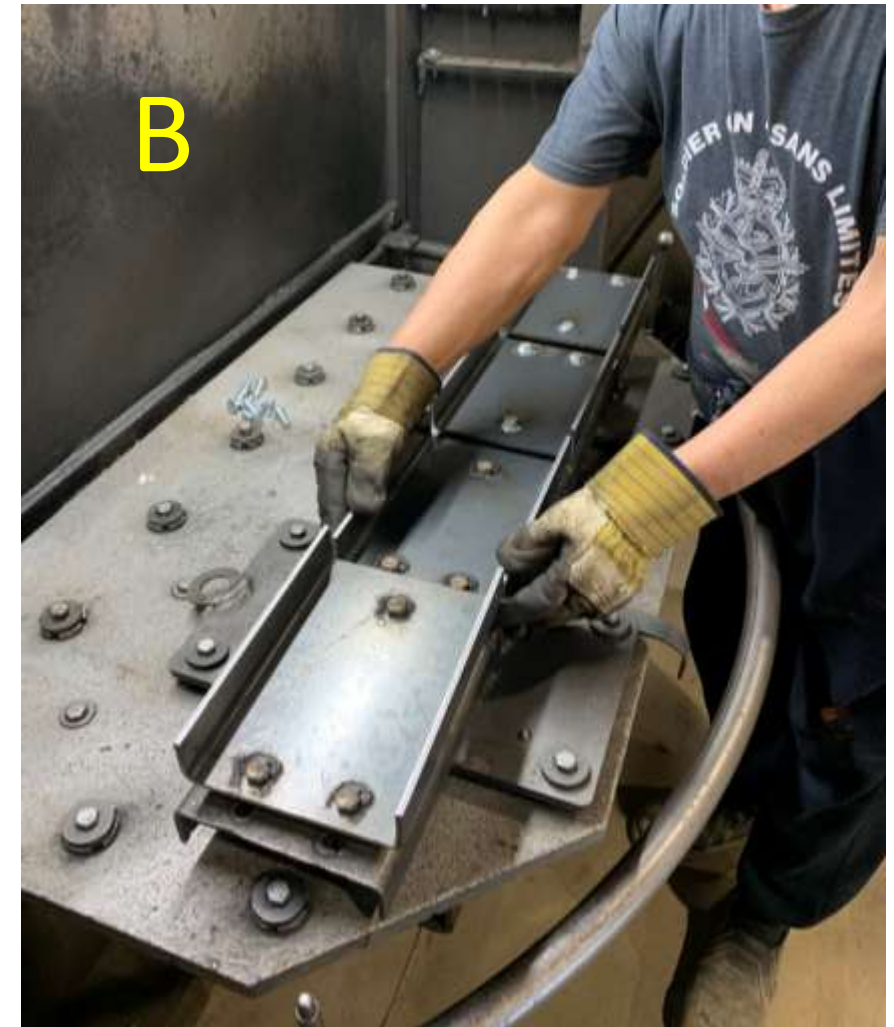
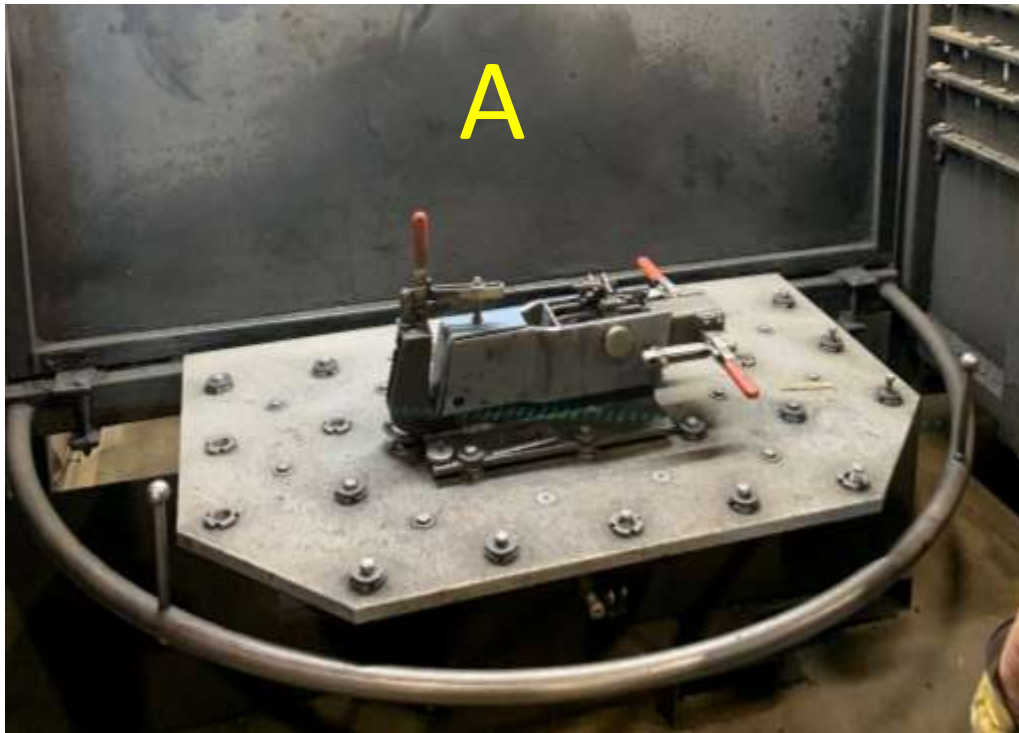




# Maximizing Output

- Part matching is critical

Weld Time of Part A  $\geq$  Setup Time Part B  
Weld Time of Part B  $\geq$  Setup Time Part A



# Return on Investment



- MKX 130 Lift Assists: 1 hr 15 min manual to 25 min robotic





# Return on Investment



- MKX 10 & 13" Transitions: 45 min manual to 17 min robotic





# Return on Investment



- MKX 10 & 13" Spout Heads: 35 min manual to 10 min robotic



# Return on Investment



- Consistent 3:1 return... per shift
- Higher quality
- Easier to staff
- Flexible



Annual salary of a welder: \$60k

Cost of a robotic welding cell: \$100k to 250k

Annual salary of a GL: \$40k

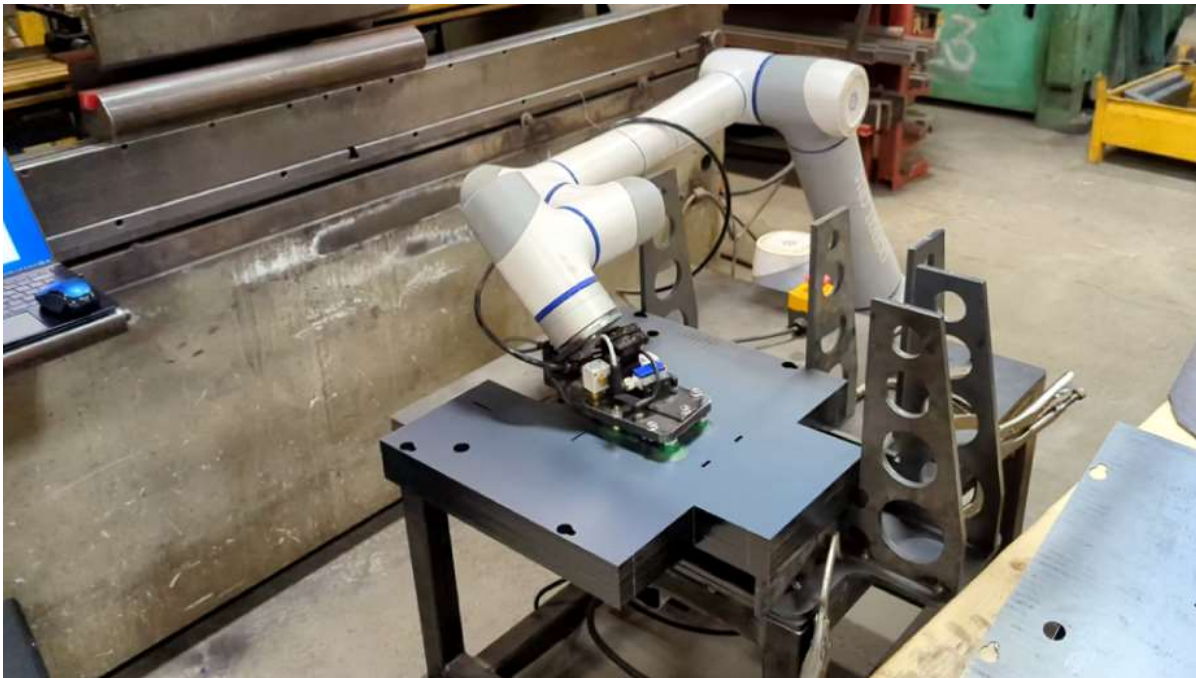
Simple Payback:

$100k \text{ to } 250k / \{(60,000 \times 6) - (40,000 \times 2)\} = 0.36 \text{ to } 0.89 \text{ years}$



# Robotic Material Handling

- The next iteration?
- Removes human error
- Great for high variety, high volume
- Cobots vs Robots





# Robotic Material Handling

- Increases programming complexity and processing time
- Fixture it if you can
- General labor is still easy to find



Pick the  
right  
parts

Build a  
robust  
fixture


Buy the  
right  
robot

Stick with it  
Involve your employees  
Eliminate variability

*Maximize output*

Questions?



**COMMITTED  
TO  QUALITY**

**AGI  WESTFIELD**

***The #1 Grain Auger Manufacturer in the World***